

Effect of Start-Up Time and Cycle Characteristic of Heat Pipe Array for a Battery Thermal Management

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ABSTRACT. *In this study, the effect of start-up time of HP-BTMS was studied by transient numerical calculation, and its cycle characteristic were also demonstrated. The numerical computation results showed that The battery temperature will reach equilibrium state as soon as the HP-BTMS is initiated at the equilibrium value. The temperature difference on the surface will dramatically increase to a high value when HP-BTMS initiated, and then gradually decrease to a low value of equilibrium state. The temperature difference on the surface in the whole cooling process will be higher than that in equilibrium state.*

KEYWORDS: *Thermal management, Heat pipe, Numerical model, Start-up time*

1. Introduction

Lithium-ion battery is the promising energy storage equipment for electric vehicles and hybrid electric vehicles for its high energy density [1, 2]. The optimum working temperature of the lithium battery is 25 °C -40 °C [3-6], the maximum temperature difference should not exceed 5 °C in one battery pack [7, 8]; otherwise, it may cause serious safety problems [6, 7]. The heat pipe cooling system which uses liquid-gas phase change without consuming extra power has become the most promising cooling method in lithium-ion battery thermal management system with excellent heat transfer performance and rapid response capability [3, 4, 9, 10].

The power battery generates heat more than 50 W [11, 12], and more during acceleration and other high charging or discharging conditions. Rao et al. [4] conducted experimental research which shows that the maximum temperature of the battery surface can be controlled below 50 °C when heat generation of the battery is less than 50 W. However, the maximum temperature difference is about 8 °C. The heat load should not exceed 30 W to maintain the surface temperature difference within 5 °C. The experiment studied of Wang et al. [13] pointed out that the battery temperature can stay below 70 °C when the heat generation per cell is between 20-40 W. Or the amount of heat generation cannot exceed 10 W in order to the maximum temperature below 40 °C. Ye et al.[14] experimentally studied different cooling strategies. The result shows that the cooling strategy with a lag time between

the start-up of HP-BTMS and battery is helpful to improve the thermal performance of HP-BTMS.

2. Numerical Setup

2.1 Geometry Models and Simplifications

Figure. 1 shows a configuration of the heat pipe cooling system for a prismatic battery pack. Between two prismatic batteries ($118\text{mm} \times 63\text{mm} \times 13\text{mm}$) sandwiched evaporator sections of four heat pipes. The heat generated in the battery is transferred to the condenser section through the heat pipe and then emitted into the coolant flow through the cooling passage ($300\text{mm} \times 60\text{mm} \times 12\text{mm}$). Each heat pipe were flattened from tubular condenser ($\Phi=6.0\text{mm}$) to rectangular evaporator section ($2.0\text{mm} \times 8.5\text{mm}$). Cross section radius of vapor core is 0.002m . The total length of the heat pipe is 0.198m . Porosity of the wick region is 0.50 . The copper cooling system is designed as similar as the heat pipe cooling system except that the heat pipes are turned to pure copper rods.

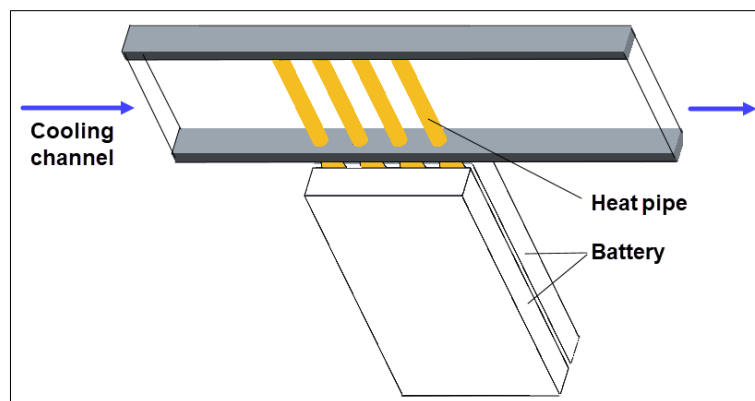


Fig.1 The Configuration of the Heat Pipe Cooling System for a Prismatic Battery Pack

It is complex and time-consuming to model all details for a battery pack cooled by heat pipe for phase changes and other phenomena in heat pipe. Even in the case of simulating one heat pipe, high computational resources are necessitated to characterize the mass and heat transfer during transient charging or discharging of the cell. Thus, one more efficient approach for numerical computation is adopted. The thermal behavior of a heat pipe on battery cooling would be treated as a thermal network of various components, and then the transient behavior can be described by first order linear ordinary differential equations [15]. Additionally, solving electro-chemical reactions of a battery is also too complicated for only presenting

the thermal behavior of battery cell (multi-layer structure). Therefore, a simplified model without considering electro-chemical reactions is applied to present the heat generation of the battery, as well as the thermal properties of a multi-layered battery cell. This approach is well validated by comparisons with experimental and numerical studies and is applied in many pieces of literature [1, 9, 11, 15].

2.2 Model Formulation of the Heat Pipe

2.3.1. Copper Shell

The thermal properties of copper were applied directly to the copper shell during this simulation because the heat transfer through the copper shell of the heat pipe is entirely conduction.

2.3.2. Wick Region

In the present study, a heat pipe with a higher maximum heat transfer limit than the target heat load has been selected to avoid drying during operation. The wick region was considered as a porous structure filled with water. A widely accepted model developed by Chi et al. [16] can be used to calculate the effective thermal conductivity of the wick region k_{wick} :

$$k_{wick} = \frac{k_l[(k_l + k_s) - (1 - \varepsilon)(k_l - k_s)]}{[(k_l + k_s) + (1 - \varepsilon)(k_l - k_s)]} \quad (1)$$

where k_l and k_s are respectively the thermal conductivity of working fluid and sintered copper powder porous wick, and ε is the porosity. In this study, the effective thermal conductivity of the wick region was calculated to be $1.814 \text{ Wm}^{-1}\text{K}^{-1}$.

The volumetric averaged density of the mixture of water and sintered copper powder porous wick could be utilized to determine to the density of the wick region by Eq. (2), and the specific heat capacity is obtained according to Eq. (3).

$$\rho_{wick} = \varepsilon\rho_l + (1 - \varepsilon)\rho_s \quad (2)$$

$$C_{wick} = [\varepsilon\rho_l C_l + (1 - \varepsilon)\rho_s C_s] / \rho_{wick} \quad (3)$$

where ρ_{wick} , ρ_l , ρ_s are respectively the densities of the wick, working fluid and copper powder, C_{wick} , C_l , C_s are respectively the specific heat capacity of the wick, working fluid and copper powder, and ε is the porosity.

2.3.3. Vapor Core

The vapor flow was considered incompressible, laminar and fully developed. By assuming the relationship between pressure drop and temperature drop in accordance with the Clapeyron equation and the ideal gas law [17, 18], the effective

thermal conductivity of the vapor core in a tubular heat pipe can be calculated by Eq.(4) [17].

$$k_{vapor} = \frac{r_v^2 L^2 \rho P_v}{8 \mu R T^2} \quad (4)$$

where r_v is the cross-section radius of the vapor core. L is the latent heat of working fluid. ρ , P_v , μ , R and T is respectively the density, the saturation pressure, the dynamic viscosity, the gas constant per unit mass and the temperature of the water vapor. The k_{vapor} was calculated as $4.69 \times 10^6 \text{ Wm}^{-1} \text{ K}^{-1}$ using the properties of saturated water vapor at a temperature of $40 \text{ }^\circ\text{C}$.

2.3 Thermal Model of the Battery

The lithium ion battery is simplified to an anisotropic cuboid, and the thermal conductivity of the vertical stacking direction of the vertical cell is smaller than the thermal conductivity of the parallel direction. The properties of the heat pipe and the battery, including the specific heat capacity, thermal conductivity density, were listed in Table 1.

It is assumed that during the entire operation process, the heat generation rate of the battery is a constant value which is regarded as the maximum power during the highest sustainable constant-current discharge rate. In the present research, the heat generation rate is in the range of 20-80 W per cell.

2.4 Numerical Procedures

In this calculation, numerical studies were performed by the commercial CFD software-ANSYS Workbench 17.2 FLUENT using a parallel solver in a double precision mode. Heat radiation transfer is negligible and was not considered.

Cartesian grids were employed to realize the spatial discretization of the domain models. Denser grids were applied in the non-slip boundary regions where the flow and temperature gradients are greater, i.e., the area around heat pipes and the heat transfer interface of the battery. The grid independent test was performed by gradually refining the mesh size (in this study, three different meshes containing 2628477, 4737970 and 7895174 cells, respectively) to ensure that the mesh size has little impact on the results. The control parameter for grid independent test was the maximum temperature of the heat transfer interface of the battery. According to the procedure described [19], the grid convergence index (GCI) was 2.81%. Figure 2 shows the mesh used in this numerical investigation.

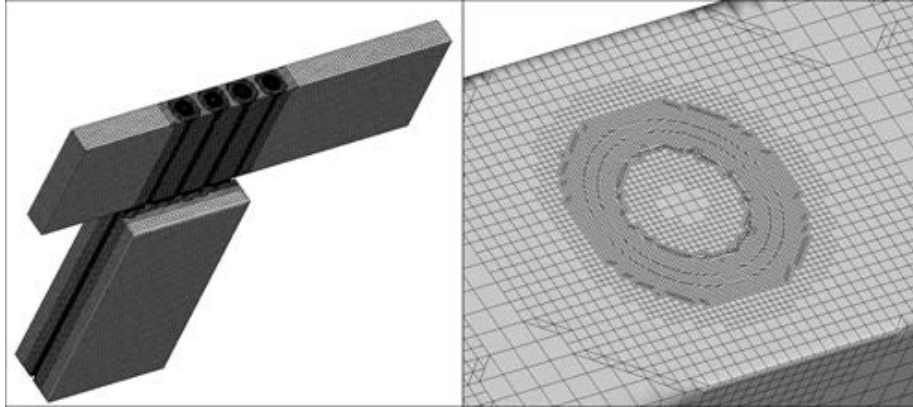


Fig.2 The Hexahedral Mesh Used in the Present Numerical Study

3. Results and Discussion

3.1. Effect of Start-Up Time of Hp-Btms

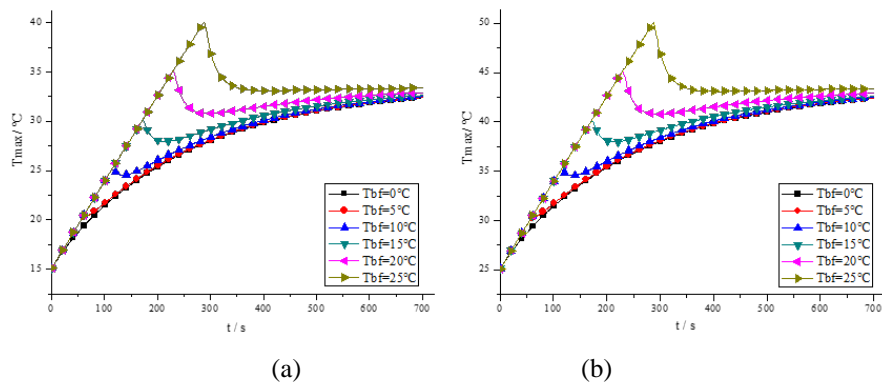
The performance of existing BTMSs is mainly discussed under the condition that the start-up of BTMS and battery is synchronized. Actually, it is unnecessary for BTMS to work immediately after the battery is initiated. The lower lithium ion diffusivity and reaction rate under low ambient temperature leads to higher over-potential and lower charge (discharge) capacity[21, 22]. The synchronized cooling possibly over cools the battery and negatively affects the power performance of battery. The unsynchronized cooling allows the battery to heat up to a higher temperature value and avoid the over cooled situation.

Ye et al.[14] pointed out that the cooling strategy with a lag time between the start-up of HP-BTMS and battery is helpful to improve the thermal performance of HP-BTMS. However, adjusting the start-up time of HP-BTMS based on the lag time is difficult due to the fact that lag time should be varied with different heat generation rates. In the present study, the temperature difference (T_{bf}) between coolant inlet and the maximum temperature of battery surface is used to control the start-up of HP-BTMS. The initiation of HP-BTMS depends on the value of T_{bf} . The definition of T_{bf} is given below:

$$T_{bf} = T_{max} - T_c \quad (6)$$

where T_{max} is the maximum temperature of battery surface; T_c is the coolant inlet temperature. The initial temperature of the cooling system and the battery is the same as the coolant inlet temperature in each condition.

The input power is set as 30 W/cell and the coolant flow rate $q_v = 2L/min$, the coolant inlet temperature is $T_c = 15^\circ C$ and $T_c = 25^\circ C$. The temperature difference (T_{bf}) studied in each case is $0^\circ C$, $5^\circ C$, $10^\circ C$, $15^\circ C$, $20^\circ C$, $25^\circ C$. The figure 3 shows the temperature responses of battery surface with different T_{bf} . For the synchronized cooling ($T_c = 0^\circ C$), it can be seen from figure 3(a) and (b) that the equilibrium temperatures are about $30^\circ C$ and $40^\circ C$ under $T_c = 15^\circ C$ and $T_c = 25^\circ C$, respectively. If HP-BTMS is initiated when $T_{bf} = 15^\circ C$ under $T_c = 15^\circ C$ and $T_c = 25^\circ C$, that is around the equilibrium temperature, T_{max} can reach equilibrium state immediately. In other words, the battery temperature will reach equilibrium state as soon as the HP-BTMS is initiated at the point where the battery temperature reaches to equilibrium value. When HP-BTMS is initiated before T_{max} reaches to equilibrium value, the time for T_{max} arriving at equilibrium state under different T_{bf} is close. When HP-BTMS starts operating after T_{max} exceeds equilibrium value, the battery can be rapidly cooled down. When the HP-BTMS starts working, the battery temperature decreases from a high value. Besides, ΔT will dramatically increase to a high value when HP-BTMS initiated, and then gradually decrease to a low value of equilibrium state as shown in figure 3(c) and (d). As a result, ΔT in the whole cooling process will be higher than the ΔT in equilibrium state, as presented in figure 3(e) and (f). This indicates that the battery temperature will fluctuate obviously when HP-BTMS starts operating after T_{max} exceeds equilibrium value.



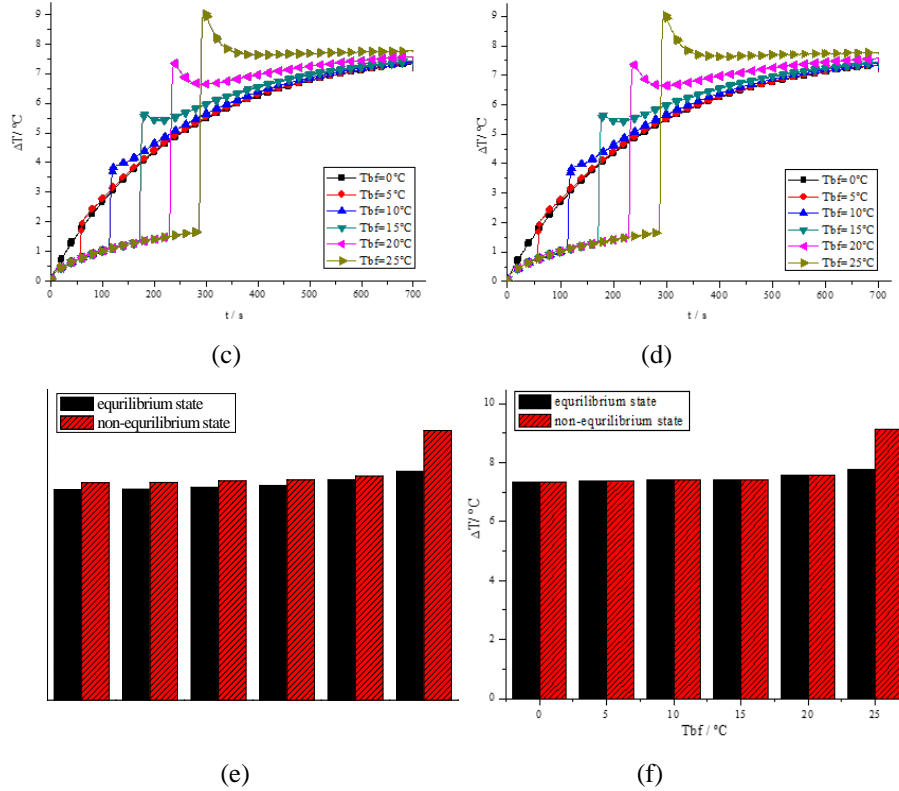


Figure 3 Thermal responses of battery with different T_{bf} (30 W/cell, $q_v = 2L/\text{min}$): T_{\max} variation with different T_{bf} under $T_c = 15^\circ\text{C}$ (a) and $T_c = 25^\circ\text{C}$ (b); temperature difference with different T_{bf} under $T_c = 15^\circ\text{C}$ (c) and $T_c = 25^\circ\text{C}$ (d); temperature fluctuation with different T_{bf} under $T_c = 15^\circ\text{C}$ (e) and $T_c = 25^\circ\text{C}$ (f).

3.2. Cycle Characteristic

The result presented in Section 3.1 indicates that it is unnecessary to initiated HP-BTMS in early working stage of battery. It might be helpful to reduce pump power consumption. In the present study, the intermittent cooling is proposed to reduce power consumption with less running time of HP-BTMS. The coolant inlet temperature and the initial temperature is set as 25°C . The coolant flow rate is set as $q_v = 2L/\text{min}$. The input power is periodically set as 30 W/ cell with lasting time of 600 s. The temperature responses of battery under intermittent cooling and constant cooling are shown in figure 4. As for the input power of 30 W/cell, the equilibrium temperature is about 40°C under $T_c = 25^\circ\text{C}$. In constant cooling, HP-BTMS

works all the time. In intermittent cooling, HP-BTMS starts operating at the time of A where T_{\max} just reaches about 40 °C, and then stops at the time of C. The T_{\max} can stay at equilibrium state as soon as HP-BTMS is initiated. That is, the HP-BTMS only works between A and C, as well as D and the end.

The maximum ΔT in intermittent cooling is no more than that in constant cooling. This indicates that the performance of intermittent cooling is basically as good as that of constant cooling. But the power consumption of BTMS can be reduced as a result of the decrease in BTMS running time.

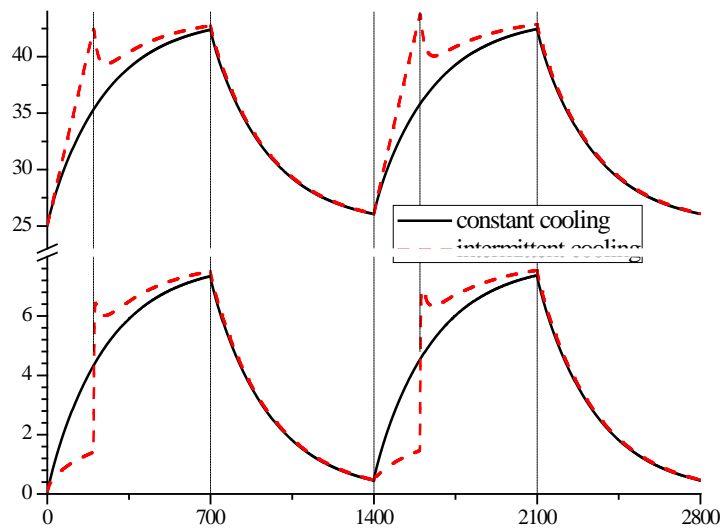


Fig.4 Variation of T_{\max} and Δt under Three Cycles ($T_{ab} = 25\text{ }^{\circ}\text{C}$, $q_v = 2\text{L}/\text{min}$).

4. Conclusion

In this study, the effect of start-up time of HP-BTMS was studied by transient numerical calculation, and its cycle characteristic were also demonstrated. The results can provide some useful guidance for HP-BTMS. The following main conclusions can be drawn:

- (1) The battery temperature will reach equilibrium state as soon as the HP-BTMS is initiated at the equilibrium value. When HP-BTMS is initiated before maximum temperature reaches to equilibrium value, the time for maximum temperature arriving at equilibrium state under different T_{bf} is almost the same. When HP-BTMS starts operating after maximum temperature exceeds equilibrium value, the battery can be rapidly cooled down.

(2) The temperature difference on the surface will dramatically increase to a high value when HP-BTMS initiated, and then gradually decrease to a low value of equilibrium state

(3) The temperature difference on the surface in the whole cooling process will be higher than that in equilibrium state.

Acknowledgments

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